

$$\min_{x \in \mathbb{R}^n} f(x), \quad f: \mathbb{R}^n \rightarrow \mathbb{R}$$

- All the first order algorithms that we saw had a $\text{poly}(1/\epsilon)$ dependence (running time) on the error ϵ .
- Start the journey towards understanding algorithms with $\text{poly} \log(1/\epsilon)$ running time dependence on ϵ .

Newton's method - uses second order oracle access to f .

$$f(x) \approx f(x_t) + \langle \nabla f(x_t), x - x_t \rangle + \frac{1}{2} \langle x - x_t, H_f(x_t) x - x_t \rangle$$

$H_f(x_t)$: Hessian of f at x_t

$$H_f(x): n \times n \text{ matrix}, \quad H_f(x)_{ij} = \frac{\partial^2 f}{\partial x_i \partial x_j}$$

Fact: f is convex iff $H_f(x)$ is PSD $\forall x$.

$$x_{t+1} := \underset{x}{\operatorname{argmin}} \quad f(x_t) + \langle \nabla f(x_t), x - x_t \rangle + \frac{1}{2} \langle x - x_t, H_f(x_t) x - x_t \rangle$$

$$x_{t+1} := x_t - H_f(x_t)^{-1} \nabla f(x_t) \quad \text{Newton's iteration}$$

Analysis in the Euclidean norm:

Assumptions: ① Strong convexity: $H_f(x) \succeq h I \quad \forall x$
(or $\lambda_{\min}(H_f(x)) \geq h$)

② Lipschitzness of the Hessian
(third order smoothness): $\|H_f(x) - H_f(y)\| \leq L \|x - y\|_2$
 $\forall x, y$

Theorem: $x_1 := x_0 - H_f(x_0)^{-1} \nabla f(x_0)$
" " " " " " $\epsilon \|\cdot\|^2$

Memem: $x_1 := x_0 - H_f(x_0) \nabla f(x_0)$

$$\Rightarrow \|x_1 - x^*\|_2 \leq \frac{L}{2h} \|x_0 - x^*\|_2^2$$

(quadratic convergence)

Issue:

Not many functions for which can get good bounds on $\frac{L}{2h}$.

Example:

$$f(x_1, x_2) := -\log(c_1 - x_1) - \log(c_1 + x_1) - \log(c_2 - x_2) - \log(c_2 + x_2)$$

For various values of c_1, c_2 , the above bound does not predict the convergence of Newton's method

Local norms: $f: \mathbb{R}^n \rightarrow \mathbb{R}$ strictly convex function i.e.

$H_f(x)$ is positive definite (PD) $\forall x \in \mathbb{R}^n$

Local inner product: $\langle u, v \rangle_x = \langle u, H_f(x) v \rangle$

Local norm: $\|u\|_x = \sqrt{\langle u, H_f(x) u \rangle}$

forms a Riemannian metric FYI

Gradient flow : steepest descent wr.t. Euclidean norm i.e.

$$\rightarrow \underset{u: \|u\|_2 = 1}{\operatorname{argmin}} \frac{d}{dt} f(x+tu) \Big|_{t=0} = - \frac{\nabla f(x)}{\|\nabla f(x)\|_2}$$

What about steepest descent wr.t. **the local norms?** i.e.

Claim: $\underset{u: \|u\|_x = 1}{\operatorname{argmin}} \frac{d}{dt} f(x+tu) \Big|_{t=0} = - \frac{H_f(x)^{-1} \nabla f(x)}{\|H_f(x)^{-1} \nabla f(x)\|_x}$

∇f :



$$\langle \nabla f(x), u \rangle$$

argmin
 $u: \|u\|_2 = 1$

↓
argmin

$u: \langle u, H_f(x)u \rangle = 1$

$$\langle \nabla f(x), u \rangle$$



$$\left| \langle H_f(x)^{-1/2} \nabla f(x), H_f(x)^{-1/2} u \rangle \right|$$

$$\leq \| H_f(x)^{-1/2} \nabla f(x) \|_2 \cdot \| H_f(x)^{-1/2} u \|_2$$

$$= \| H_f(x)^{-1/2} \nabla f(x) \|_2$$

$= 1$

For $u = \frac{-H_f(x)^{-1} \nabla f(x)}{\| H_f(x)^{-1} \nabla f(x) \|_2}$, $\|u\|_2 = 1$ by construction

$$\langle \nabla f(x), u \rangle = - \frac{\langle \nabla f(x), H_f(x)^{-1} \nabla f(x) \rangle}{\| H_f(x)^{-1} \nabla f(x) \|_2}$$

$$= - \frac{\| H_f(x)^{-1/2} \nabla f(x) \|_2^2}{\| H_f(x)^{-1} \nabla f(x) \|_2}$$

$$= - \frac{\sqrt{\langle H_f(x)^{-1} \nabla f(x), H_f(x) H_f(x)^{-1} \nabla f(x) \rangle}}{\| H_f(x)^{-1} \nabla f(x) \|_2}$$

$$= - \| H_f(x)^{-1/2} \nabla f(x) \|_2$$

Newton's increment:

$$x_{t+1} := x_t - H_f(x_t)^{-1} \nabla f(x_t)$$

$n(x_t)$

Potential function: $\|n(x)\|_x$

Assumption: Hessians at x & y are close if x & y close

Let $\delta_0 < 1$ be some fixed constant.

Definition: f satisfies the Newton-Local (NL) condition
for $\delta_0 < 1$ $\forall \forall 0 \leq \delta \leq \delta_0$, $\forall x, y$ s.t.
 $\|y-x\|_x \leq \delta$,
 $(1-3\delta) H(x) \leq H(y) \leq (1+3\delta) H(x)$

($A \leq B$ if $B-A \succeq 0$)

Theorem: Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be a strictly convex function satisfying
the NL condition for $\delta_0 = 1/6$. Then

$$x_1 := x_0 - n(x_0)$$
$$\text{s.t. } \|n(x_0)\|_{x_0} \leq 1/6$$

$$\Rightarrow \|n(x_1)\|_{x_1} \leq 3 \|n(x_0)\|_{x_0}^2$$

Lemma: Suppose x, y s.t. $\|y-x\|_x \leq 1/6$. Then

the x & y local norms are close i.e. $\forall u$

$$\textcircled{1} \quad \frac{1}{2} \|u\|_x \leq \|u\|_y \leq 2 \|u\|_x$$

$$\textcircled{2} \quad \frac{1}{2} \|u\|_{H_f(x)^{-1}} \leq \|u\|_{H_f(y)^{-1}} \leq 2 \|u\|_{H_f(x)^{-1}}$$

$$\left(\|u\|_A = \sqrt{\langle u, Au \rangle} \right)$$

Of:

From the NL condition, we have that

$$\left(\begin{array}{l} A \leq B \\ \Rightarrow B^{-1} \leq A^{-1} \end{array} \right)$$

$$\frac{1}{2} H_f(y) \leq H_f(x) \leq 2 H_f(y)$$

$$\frac{1}{2} H_f(y)^{-1} \leq H_f(x)^{-1} \leq 2 H_f(y)^{-1}$$

e.g. $\Rightarrow \forall u \frac{1}{2} \langle u, H_f(y) u \rangle \leq \langle u, H_f(x) u \rangle$
 $\Rightarrow \|u\|_y \leq 2 \|u\|_x$